

Electronics Real Time Programming

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- main program is a software *state machine*.

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repeated until shut down

Arduino Serial sample code

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```
void setup() {  
    Serial.begin(9600);  
    while (!Serial) {  
        ;  
    }  
}  
  
void loop() {  
    if (Serial.available() > 0) {  
        inByte = Serial.read();  
        Serial.write(inByte);  
    }  
}
```


PySpidev sample code

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```
import spidev
spi = spidev.SpiDev()
spi.open(0,0) #port , device
# use port 0, chip select CE0
while True:
    strval = raw_input(" val (0...255 , q=quit):")
    if strval == 'q':
        break
    else:
        value = int (strval)
        dummy = spi.xfer2 ([49 , value])
spi.close()
```

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Real-time sequencing options

① **polling**

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use events to indicate task completion

④ **capture/compare**

tasks run at intervals, completion indicated by event
probably includes interrupts

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- The last two make the *program structure* depend on *response to system events*.